Synchrony, Phase-Shift Synchrony, and Synchony-Breaking

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Networks and Coupled Systems (1)

 $\Delta = \{x_1 = x_2\}$ is flow-invariant

$$\dot{x}_{1} = f(x_{1}, x_{3})$$

$$\dot{x}_{2} = f(x_{2}, x_{1})$$

$$\dot{x}_{3} = f(x_{3}, x_{2})$$

$$x_{1}, x_{2}, x_{3} \in \mathbf{R}^{k}$$

 $\Delta = \{x_1 = x_2 = x_3\}$ is flow-invariant

$$(1) \longrightarrow (2) \longrightarrow (3) \qquad \begin{array}{c} \dot{x}_1 &=& f(x_1, x_1, \lambda) \\ \dot{x}_2 &=& f(x_2, x_1, \lambda) \\ \dot{x}_3 &=& f(x_3, x_2, \lambda) \end{array} \qquad \begin{array}{c} x_1, x_2, x_3 \in \mathbf{R}^k \\ \dot{x}_3 &=& f(x_3, x_2, \lambda) \end{array}$$

 $\Delta = \{x_1 = x_2 = x_3\}$ is flow-invariant

- Polydiagonal is subspace $\Delta = \{x_c = x_d \text{ for some subset of cells}\}$
- Synchrony subspace is flow-invariant polydiagonal
- Synchrony subspace corresponds to solutions with EXACT synchrony between subsets of nodes

Chain with Back Coupling



• $\Delta = \{ \mathbf{x_1} = \mathbf{x_4} = \mathbf{x_7}; \ \mathbf{x_2} = \mathbf{x_5}; \ \mathbf{x_3} = \mathbf{x_6} \}$ is flow-invariant

• Δ is a synchrony subspace

Balanced Coloring

- $\bullet \ {\rm Let} \ \Delta$ be a polydiagonal
- Color equivalent cells the same color if cell coord's in Δ are equal
- Coloring is balanced if all cells with same color receive equal number of inputs from cells of a given color



• Theorem 1: synchrony subspace \iff balanced

Stewart, G., and Pivato (2003); G., Stewart, and Török (2005)

2D-Lattice Dynamical Systems

- square lattice with nearest neighbor coupling
- Network architecture is more important than symmetry
- Form two-color balanced relation



 Each black cell connected to two black and two white Each white cell connected to two black and two white
 Stewart, G. and Nicol (2004)

Lattice Dynamical Systems

• On Black/White diagonal interchange black and white





Result is **balanced**

• Continuum of different synchrony subspaces





Lattice Dynamical Systems

- Architecture is important
- For square lattice with nearest and next nearest neighbor coupling
 - No infinite families
 - For each k a finite number of balanced k colorings
 - All balanced colorings are doubly-periodic

Antoneli, Dias, G., and Wang (2004)

Phase-Shift Synchrony: Two Identical Cells

• Rigid time-periodic solutions exist where cells oscillate in phase

$$x_2(t) = x_1(t)$$

Not surprising since $x_1 = x_2$ is flow-invariant

 Robust time-periodic solutions exist where cells oscillate a half-period out-of-phase

$$x_2(t) = x_1(t + \frac{T}{2})$$

Spatio-Temporal Symmetries

- A symmetry of $\dot{x} = F(x)$ is linear map γ that takes sol'ns to sol'ns
- Let x(t) be a time-periodic solution

 $H = \{\gamma \in \Gamma : \gamma\{x(t)\} = \{x(t)\}\}$ spatiotemporal symm's

- $\gamma \in H \Longrightarrow \theta \in \mathbf{S}^1$ such that $\gamma x(t) = x(t + \theta)$
- Example: $H = \mathbf{Z}_2(1\ 2); \quad \theta = 0 \quad \text{or} \quad \theta = \frac{T}{2}$

Three-Cell Bidirectional Ring: $\Gamma = S_3$

• Out-of-phase: $H = <(1 \ 3)(2) >$

$$x_3(t) = x_1\left(t + \frac{T}{2}\right)$$
 and $x_2(t) = x_2\left(t + \frac{T}{2}\right)$



G. and Stewart (1986)

Discrete Rotating Wave

• Out-of-phase: $H = \langle (1 \ 3) \rangle$

 $x_2(t) = x_1\left(t + \frac{T}{3}\right)$ and $x_3(t) = x_2\left(t + \frac{T}{3}\right) = x_1\left(t + \frac{2T}{3}\right)$



Quotient Networks: Self-Coupling & Multiarrows

• Balanced two-coloring of bidirectional ring

$$\begin{aligned} \dot{\mathbf{x}}_1 &= \mathbf{f}(\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3) \\ \dot{\mathbf{x}}_2 &= \mathbf{f}(\mathbf{x}_2, \mathbf{x}_3, \mathbf{x}_1) \\ \dot{\mathbf{x}}_3 &= \mathbf{f}(\mathbf{x}_3, \mathbf{x}_1, \mathbf{x}_2) \end{aligned}$$

where
$$\mathbf{f}(\mathbf{x}, \mathbf{y}, \mathbf{z}) = \mathbf{f}(\mathbf{x}, \mathbf{z}, \mathbf{y})$$

- $\Delta = \{x_1 = x_2\}$ is a synchrony subspace
- Quotient network:

$$\dot{\mathbf{x}}_1 = \mathbf{f}(\mathbf{x}_1, \mathbf{x}_1, \mathbf{x}_3) \dot{\mathbf{x}}_3 = \mathbf{f}(\mathbf{x}_3, \mathbf{x}_1, \mathbf{x}_1)$$

where $\mathbf{f}(\mathbf{x},\mathbf{y},\mathbf{z}) = \mathbf{f}(\mathbf{x},\mathbf{z},\mathbf{y})$



Asym Network; Symmetric Quotient



• Quotient is bidirectional 3-cell ring with D₃ symmetry



• Rigid phase shift; no symmetry

- Let ${\mathcal G}$ be a network
- Pattern of phase-shift synchrony is quotient network Q and permutation symmetry $\sigma : Q \to Q$
- A *T*-periodic solution Z(t) to a *G*-admissible system
 has pattern of phase-shift synchrony Q and σ) if
 - $\{Z(t)\} \subset \Delta_Q$; Y(t) is Z(t) viewed in quotient network
 - $\sigma Y(t) = Y\left(t + \frac{T}{m}\right)$ where m is order of σ

Consequences of Pattern of Phase-Shift Synchrony

- $\{Z(t)\} \subset \Delta_{\mathcal{Q}} \Longrightarrow z_c(t) = z_d(t)$ when nodes $c, d \in \mathcal{G}$ have same color
- $\sigma = \sigma_1 \cdots \sigma_s$ product of disjoint cycles of orders $m_1, \ldots, m_s \leq m$
- Renumber nodes in Q so that $\sigma_1 = (1 \cdots m_1)$. Let Y(t) be Z(t) viewed in Q. Then $\sigma Y(t) = Y(t + \frac{T}{m})$ implies

$$y_2(t) = y_1(t + \frac{T}{m})$$

$$\vdots$$

$$y_{m_1}(t) = y_{m_1-1}(t + \frac{T}{m})$$

$$y_1(t) = y_{m_1}(t + \frac{T}{m})$$

- So $y_1(t) = y_1(t + \frac{m_1}{m}T)$ and y_1 has period $T_1 = \frac{m_1}{m}T$
- Cycles of different lengths in σ imply multirhythms

Rigid Phase-Shift \Leftrightarrow Pattern of Phase-Shift Synchrony

- $Z(t) = (z_1(t), \dots, z_N(t))$ is hyperbolic *T*-periodic solution
- Phase-shift synchrony between nodes *i*, *j*

$$z_i(t) = z_j(t + \theta T)$$
 where $0 \le \theta < 1$

- Phase-shift synchrony is **rigid** if perturbing system leads to periodic solution with same phase-shift θ
- Theorem 2: Assume path-connected network *G*. Nonzero rigid phase-shift synchrony iff phase-shift forced by some symmetry on a quotient network

Stewart and Parker (2008, 2009); G., Romano and Wang (2010, 2011)

Regular Three Cell Networks

- Regular network: one type of node and one type of coupling
- Valency = ν = total number of inputs per cell

$$a_{i1} + a_{i2} + a_{i3} = \nu$$
 for $j = 1, 2, 3$

• 34 regular three-cell valency 2 networks

Leite and G. (2006)

13 Three-Cell Transitive Networks



























21 Three-Cell Feed-Forward Networks









2

3





9.























$$\bullet \bigcirc 1 \longrightarrow 2 \longrightarrow 3 \quad \begin{array}{c} \dot{x}_1 &=& f(x_1, x_1, \lambda) \\ \dot{x}_2 &=& f(x_2, x_1, \lambda) \\ \dot{x}_3 &=& f(x_3, x_2, \lambda) \end{array} J = \begin{bmatrix} \alpha + \beta & 0 & 0 \\ \beta & \alpha & 0 \\ 0 & \beta & \alpha \end{bmatrix}$$

• Network supports solution by Hopf bifurcation where $x_1(t)$ equilibrium $x_2(t), x_3(t)$ time periodic



G., Nicol, and Stewart (2004); Elmhirst and G. (2005)

Eigenspace Types of Jacobians

- 20 networks have real simple eigenvalues
- Simple complex eigenvalues: 2, 14, 18, 19, 24

• Double with two synchrony-breaking eigenvectors: 4, 7, 8



• Nilpotent: 3; 6, 11, 27, 28



• **Double** with synchrony preserving eigenvector: 12

Leite and G. (2006)

Nilpotent Hopf Bifurcation

• Networks 3, 28, 27: branches that grow at $\lambda^{\frac{1}{6}}$



• Networks 6, 11: two or four branches that grow $\lambda^{\frac{1}{2}}$



• Regular five-cell network: two branches that grow λ



Elmhirst and G. (2005)

Nilpotent Hopf in Network 27



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